# **Bifurcations of an age-structured** predator-prey model





## **Q.** Richard (joint work with A. Perasso<sup>\*</sup>)

Laboratoire de Mathématiques de Besançon (LMB) \* Laboratoire Chrono-Environnement Université Bourgogne Franche-Comté, France quentin.richard@univ-fcomte.fr



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## Abstract

The relationships between a predator and its prey are subject of numerous studies in ecology. Since the first mathematical model, describing over time such trophic interactions was introduced ([3], [5]), the so-called Lotka Volterra equations, and predator-prey models are still a wide subject of study in population dynamics. For a better modelling, it is interesting to consider an age-structured prey population, leading to a PDE of transport type. Once the problem is well-posed, we use some spectral analysis results [2] and a stability analysis of the equilibria [6] to study the time asymptotic behaviour of the solutions. We prove in [4] the existence of two thresholds for the extinction and the explosion of both populations. Finally, using numerical computations, we show that other behaviours can appear.

## 1. Lotka-Volterra model

Let (x(t), y(t)) be the populations at time t of prey and predator. In the 1920s, Alfred Lotka [3] and Vito Volterra [5] proposed the ODE model

 $\begin{cases} x'(t) = ax(t) - bx(t)y(t), \\ y'(t) = cx(t)y(t) - dy(t), \end{cases}$ 

with positive parameters and

• *a* is the **birth** rate of the prey:

• *d* is the **mortality** rate of the predator;

• the nonlinear term models the **predation**.

This models gives rise to periodic solution which explains the oscillation of lynx and snowshoe hare in Canada.



Figure 1: Periodic solutions

## 2. Age-structured model

## 4. Equilibria

Define

 $a_1 = \sup\{a \ge 0 : |\operatorname{supp}(\gamma) \cap (0, a)| = 0\} < \infty;$  $R_0 = \int_0^\infty \beta(a) e^{-\int_0^a \mu(s) ds} ds \text{ (extinction threshold)};$  $R_{-} = \int_{0}^{a_{1}} \beta(a) e^{-\int_{0}^{a} \mu(s) ds} da \text{ (unboundedness threshold).}$ Theorem 2. (Number of equilibrium)

$R_0 < 1$	$R_0 > 1, R < 1$	$R_{-} > 1$
$E_0$	$E_0$ and $E_2$	$E_0$

where  $E_0 = (0, 0)$  and  $E_2$  is a positive steady state.

## 5. Stability analysis

Using classical results of spectral analysis ([2], [6]), we get the following characteristic equation for  $E_0$ 

 $\int^{\infty} \beta(a) e^{-\int_{0}^{a} [\lambda + \mu(s)] ds} da = 1$ 

which implies

**Theorem 3. (Stability of**  $E_0$ ) 1.  $R_0 < 1 \Rightarrow E_0$  is globally stable (Figure 2) **2**.  $R_0 > 1 \Rightarrow E_0$  is unstable.



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**Figure 5:** Convergence to  $E_2$ 

$R_0 < 1$	$R_0>1$ and $R<1$	$R_{-} > 1$
Extinction	Coexistence	Explosion

## 7. Perspectives

Let  $Z = \mathcal{C}[-\tau, 0] \times \mathbb{R}$  and suppose that  $\gamma(a) = \gamma_0 \mathbf{1}_{[\tau, +\infty[}(a),$  $\beta(a) = \beta_0 \mathbf{1}_{[\tau, +\infty[}(a).$  $\mu \equiv \mu_0,$ We thus get the following delay system

$$\begin{cases} x'(t) = \beta_0 e^{-\mu_0 \tau} x(t-\tau) - (\mu_0 + \gamma_0 y(t)) x(t), \\ y'(t) = \alpha \gamma_0 x(t) y(t) - \delta y(t), \\ x(\theta) = \phi(\theta), \theta \in [-\tau, 0], \quad y(0) = y_0, \end{cases}$$

where  $(\phi, y_0) \in Z$ . When  $R_0 > 1$ , the equilibrium is

 $E^* = \left(\frac{\delta}{---}, \frac{\beta_0 e^{-\mu_0 \tau} - \mu_0}{----}\right) = (x^*, y^*).$ 

Consider that birth and death of each prey depend on his **age**  $(a \ge 0)$ . We get the generalized PDE structured model

$$\begin{cases} \partial_t x + \partial_a x = -\mu(a)x - y(t)\gamma(a)x, \\ y'(t) = \alpha y(t) \int_0^\infty \gamma(a)x(t,a)da - \delta y(t), \\ x(t,0) = \int_0^\infty \beta(a)x(t,a)da, \\ x(0,.) = x_0, \quad y(0) = y_0, \end{cases}$$
(1)

with  $\delta > 0$  and where •  $\mu, \gamma, \beta \in L^{\infty}_{+}(\mathbb{R}_{+})$  are age-dependent functions; •  $\alpha \in (0, 1)$  is the assimilation coefficient of ingested preys.



## We assume

 $\exists \mu_0 > 0 : \mu(a) \ge \mu_0$  f.a.e.  $a \ge 0$ .

(H1)

Let  $X = L^1(\mathbb{R}_+) \times \mathbb{R}$  and  $X_+$  his nonnegative cone. Consider the operator  $A: D(A) \subset X \to X$ , by

 $A\begin{pmatrix}\phi\\z\end{pmatrix} = \begin{pmatrix}-\phi' - \mu\phi\\-\delta z\end{pmatrix},$ 

 $D(A) = \{(\phi, z) \in W^{1,1}(\mathbb{R}_+) \times \mathbb{R}, \phi(0) = \int_0^\infty \beta(a)\phi(a)da\}.$ and define the function  $f: X \to X$  by

 $f(\phi, z) = \begin{pmatrix} -z\gamma(.)\phi(.) \\ \alpha z \int_0^\infty \gamma(a)\phi(a)da \end{pmatrix}.$ 



**Figure 2:** Convergence to  $E_0$  when  $R_0 < 1$ 

## 6. And for R0>1 ?

## We suppose

 $\exists \eta_1 > 0, \exists 0 < \underline{a} < \overline{a} : \beta(a) \ge \eta_1, a \in (\underline{a}, \overline{a})$ (H2) It means that preys of a certain range of age have a high ability to reproduce. We find a bassin of attraction  $X_p$  such that

Theorem 4. (Unbounded solutions)

If  $R_{-} > 1$  then  $\lim_{t \to +\infty} \|x(t,.)\|_{L^{1}} = +\infty$  and  $\lim_{t\to+\infty} y(t) = +\infty$  for every  $(x_0, y_0) \in X_p$  (Figure 3).



$$- \left(\alpha\gamma_0, \gamma_0\right) \left(\alpha\gamma_0, \gamma_0\right)$$

We get the characteristic equation  $p(\lambda) + q(\lambda)e^{-\lambda\tau} = 0$ ,

where  $\begin{cases} p(\lambda) = \lambda^2 + \lambda \beta_0 e^{-\mu_0 \tau} + \delta \gamma_0 y^*, \\ q(\lambda) = -\lambda \beta_0 e^{-\mu_0 \tau}. \end{cases}$ 

Absolute stability result from [1] implies

## Theorem 5. (Local stability)

If  $\tau \sqrt{\delta y^* \gamma_0} / 2\pi \notin \mathbb{Z}$  then  $E^*$  is loc. asympt. stable. Let  $S = \{(\varphi, y) \in Z, \int_0^\tau \varphi > 0, y > 0\}$  then

## Theorem 6. (Periodic solution)

For every  $(\phi, y_0) \in S$  the solution of (2) converges to a  $\tau$ -periodic function.



## **Figure 6:** Convergence to $E^*$

A future work will be to prove that the only  $\tau$ -periodic solution is **constant**, hence the global stability of  $E_2$  in S follows.

## We then get the abstract Cauchy Problem

 $\begin{cases} \frac{d}{dt} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = A \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} + f(x(t), y(t)), \\ (x(0), y(0) = (x_0, y_0) \in X. \end{cases}$ 

Classical results of the semigroup theory proves that

Theorem 1. (Existence/uniqueness) For all  $(x_0, y_0) \in X_+$ , Problem (1) has a unique mild solution  $(x, y) \in \mathcal{C}(\mathbb{R}_+, X_+)$ .

## **Figure 3:** Unbounded solutions

When  $R_0 > 1$  and  $R_- < 1$ , numerical simulations shows • either convergence to a limit cycle (Figure 4); • or convergence to  $E_2$  (Figure 5).



Figure 4: Limit cycle

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